

Flexible complete Models with
stochastic volatility
generalizing Hobson-Rogers

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1 Hobson-Rogers Model

Hobson and Rogers proposed several complete stochastic volatility models. Fix a time horizon $T > 0$. Given a price process $(P_t)_{0 \leq t \leq T}$, which is a positive, square integrable Ito process on a stochastic basis $(\Omega, \mathcal{F}_T, P)$ with one-dimensional Brownian motion $(B_t)_{0 \leq t \leq T}$, we introduce $Z_t := \ln(e^{-rt}P_t)$, where $r \geq 0$ denotes the interest rate. Then we assume for a positive parameter $\lambda > 0$ the 2-dimensional Markov process (Z_t, S_t)

$$dZ_t = \mu(S_t)dt + \sigma(S_t)dB_t$$

$$dS_t = dZ_t - \lambda S_t dt = (\mu(S_t) - \lambda S_t)dt + \sigma(S_t)dB_t,$$

$$Z_0 = z, S_0 = s,$$

for volatility and drift vector fields μ, σ which satisfy the usual Lipschitz assumptions and $\sigma(s) > 0$ for $s \in \mathbb{R}$. The process $(S_t)_{0 \leq t \leq T}$ is the first offset function of $(Z_t)_{0 \leq t \leq T}$ with parameter $\lambda > 0$.

Defining

$$\theta(s) = \frac{1}{2}\sigma(s) + \frac{\mu(s)}{\sigma(s)},$$

where we assume additionally that the measure Q_t on \mathcal{F}_t given through

$$\frac{dQ_t}{dP} = \exp\left(-\int_0^t \theta(S_u)dB_u - \frac{1}{2}\int_0^t \theta(S_u)^2 du\right)$$

is well-defined for $0 \leq t \leq T$ and that $Q := Q_T$ is a probability measure equivalent to P on \mathcal{F}_T . Then the process $\widetilde{B}_t := B_t + \int_0^t \theta(S_u)du$ is a Q -Brownian motion and the stochastic differential equation reads as follows with respect to $(\widetilde{B}_t)_{0 \leq t \leq T}$

$$\begin{aligned} dZ_t &= -\frac{1}{2}\sigma(S_t)^2 dt + \sigma(S_t)d\widetilde{B}_t, \\ dS_t &= -\left(\frac{1}{2}\sigma(S_t)^2 + \lambda S_t\right)dt + \sigma(S_t)d\widetilde{B}_t, \\ Z_0 &= z, S_0 = s \end{aligned}$$

for $0 \leq t \leq T$.

The discounted price process $(e^{-rt}P_t)_{0 \leq t \leq T}$ is a Q -martingale and we can apply the classical no-arbitrage pricing arguments. In particular the market is complete since this is the only martingale measure equivalent to P . Under Q the price process satisfies

$$dP_t = rP_t dt + \sigma(S_t)P_t d\widetilde{B}_t$$

Therefore the price of a European claim, which is given by a measurable function with at most linear growth $q : \mathbb{R} \rightarrow \mathbb{R}$, is defined by

$$V(P_t, S_t, T - t) = e^{r(T-t)} E(q(P_T) | \mathcal{F}_t)$$

for $0 \leq t \leq T$ via the Markov property. If the Lie algebra spanned by the two vector fields

$$\begin{aligned} (z, s) &\mapsto \begin{pmatrix} \sigma(s) \\ \sigma(s) \end{pmatrix} \\ (z, s) &\mapsto \begin{pmatrix} -\frac{1}{2}\sigma(s)^2 - \frac{1}{2}\sigma(s)'\sigma(s) \\ -\frac{1}{2}\sigma(s)^2 - \lambda s - \frac{1}{2}\sigma(s)'\sigma(s) \end{pmatrix} \end{aligned}$$

or equivalently

$$(z, s) \mapsto \begin{pmatrix} \sigma(s) \\ \sigma(s) \end{pmatrix} \quad \text{and} \quad (z, s) \mapsto \begin{pmatrix} 0 \\ \lambda s \end{pmatrix}$$

spans the tangent space \mathbb{R}^2 pointwise on $\mathbb{R}_{>0} \times \mathbb{R}$ (which is the case for non-vanishing σ and $\lambda \neq 0$), then by Hörmander's "Sum of the Squares" we know that f is a smooth function on $\mathbb{R}_{>0} \times \mathbb{R} \times]0, T[$ and satisfies the boundary condition $f(p, s, 0) = q(p)$ for all $(p, s) \in \mathbb{R}_{>0} \times \mathbb{R}$.

One particular choice for σ is a smooth vector field $\sigma : \mathbb{R} \rightarrow \mathbb{R}$ such that

$$\sigma(s)^2 := \eta^2(1 + \epsilon s^2)$$

on some ball with large radius $R > 0$ and constant outside for fixed $\epsilon \geq 0$. Here η is referred to as minimal level of implied volatility and $\epsilon \geq 0$ denotes a parameter calibrating the influence of the first offset process $(S_t)_{t \geq 0}$ on the stochastic evolution of the price process. Furthermore the option price depends smoothly on the parameters η, ϵ and λ on the respective intervals of definition. By standard methods we can find a version of the solution $(Z_t, S_t)_{0 \leq t \leq T}$ of the stochastic differential equation, which depends in a smooth way on the initial values and the parameters.

In order to fit a model – with a finite number of parameters – to market data, one needs to solve an inverse problem:

- solve the associated PDE often and look which outcomes fit the data best.
- choose a best choice and verify.

Such procedures are expensive and (sometimes) unstable. The value of tractable formulas gets particularly visible.

In mathematical finance we model price behaviours by semi-martingales $(S_t^{(\epsilon)})_{t \geq 0}$, which often depend on additional parameters, here denoted by $\epsilon \geq 0$. We propose a method, which allows to calculate derivatives of the function $\epsilon \mapsto E(\phi(S_T^{(\epsilon)}))$ efficiently. To be more precise, we are able to prove that – under some technical assumptions – there exist random variables $\pi^{(n)}$ such that

$$\frac{\partial^n}{\partial \epsilon^n} E(\phi(S_T^{(\epsilon)})) = E(\phi(S_T^{(\epsilon)}) \pi^n).$$

This approach provides

- explicit algorithms how to calculate the weights, even if the functions in question are not real analytic.
- probabilistic approaches for approximations of model prices (Monte Carlo evaluations).
- the method works well in the hypo-elliptic context.

2 Partial Integration and Taylor expansion of Prices

Let (Ω, \mathcal{F}, P) be a probability space, which is generated by a one-dimensional Brownian motion $(B_t)_{0 \leq t \leq T}$ for some $T > 0$, i.e. $\mathcal{F} = \mathcal{F}_T$. For the reader who is familiar with Ito-integration, but does not feel comfortable with Malliavin Calculus, we list the following simple rules, which allow to follow all calculations which are done in the article:

1. The Malliavin derivative associates to random variables (in its domain of definition) $X \in \text{dom}(D) \subset L^2(\Omega)$ a not necessarily adapted process

$$(D_s X)_{0 \leq s \leq T} \in L^2([0, T] \times \Omega).$$

The Malliavin derivative is a closed, densely defined, unbounded linear operator and the following rules hold,

$$D_s(1_\Omega) = 0$$

$$D_s\left(\int_0^T \sigma(s)dB_s\right) = \sigma(s)1_{[0,T]}(s),$$

$$D_s(\phi(X_1, \dots, X_n)) = \sum_{i=1}^n \frac{\partial}{\partial x^i} \phi(X_1, \dots, X_n) D_s X_i$$

for $X_i \in \text{dom}(D)$, $i = 1, \dots, n$ and σ a square-integrable, deterministic function on $[0, T]$. ϕ is given as a C^1 -function on \mathbb{R}^n .

2. The adjoint of the Malliavin derivative is the Skorohod integral δ , which associates to a not necessarily adapted process $(Y_s)_{0 \leq s \leq T} \in \text{dom}(\delta) \subset L^2([0, T] \times \Omega)$ a random variable $\delta(s \mapsto Y_s) \in L^2(\Omega)$. The Skorohod integral is a closed, densely defined, unbounded linear operator and the following basic partial integration formula holds true

$$E(X \delta(s \mapsto Y_s)) = E\left(\int_0^T (D_s X) Y_s ds\right)$$

on the respective domains. The most important, non-trivial assertion on Skorohod integration is the relation to Ito-integration: namely, for all square-integrable, predictable processes $(Y_s)_{0 \leq s \leq T}$ we obtain that $(Y_s)_{0 \leq s \leq T} \in \text{dom}(\delta)$ and

$$\delta(s \mapsto Y_s) = \int_0^T Y_s dB_s.$$

3. By extension of the derivative operator D on L^p -spaces we obtain domains of definition $\mathcal{D}^{p,1} \subset L^p(\Omega)$. By definition of iterated derivatives on the respective domains we obtain domains of definition $\mathcal{D}^{p,n} \subset L^p(\Omega)$, where the Malliavin-derivative can be applied n times. Smooth random variables are those, which lie in the domain of each derivative operator in each L^p , i.e.

$$\mathcal{D}^\infty = \bigcap_{p \geq 1} \bigcap_{n \geq 0} \mathcal{D}^{p,n}.$$

A fortiori smooth random variables are closed under composition with smooth, polynomially bounded functions and allow Skorohod integration up to arbitrary orders.

4. For Skorohod integrable process $(u_s)_{0 \leq s \leq T}$ and $F \in \mathcal{D}^\infty$ with $E(\int_0^T F^2 u_s^2 ds) < \infty$, the process $(Fu_s)_{0 \leq s \leq T}$ is Skorohod-integrable and

$$\delta(s \mapsto u_s F) = F \delta(s \mapsto u_s) - \int_0^T u_s D_s F ds$$

holds true.

5. The Malliavin covariance matrix is a real-valued random variable in the one-dimensional case,

$$\gamma(X) := \int_0^T (D_s X)^2 ds.$$

If $\gamma(X)$ is invertible almost surely, then X has a density with respect to Lebesgue's measure.

We shall deal with families of random variables $\epsilon \mapsto G_\epsilon$ such that

- for all $\epsilon \geq 0$ the random variable and all its derivatives with respect to ϵ are smooth, i.e. $\frac{\partial^k}{\partial \epsilon^k} G_\epsilon \in \bigcap_{p \geq 1} \bigcap_{n \geq 0} \mathcal{D}^{p,n}$ for $k \geq 0$, together with all Malliavin derivatives. The derivatives are taken with respect to the topology of \mathcal{D}^∞ , which is equivalent to the assertion that the maps $\epsilon \mapsto \eta(G_\epsilon)$ are smooth, for all continuous linear functionals $\eta : \mathcal{D}^\infty \rightarrow \mathbb{R}$.

We denote this space by $C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$. Notice in particular that this space is a (smooth) algebra of random variables, where the Skorohod integral and the Malliavin derivative are well-defined. In particular the constant curve $\epsilon \mapsto 1$ satisfies the requirements. Observe the following rules of differentiation:

- Malliavin derivatives and Skorohod integrals commute with derivatives with respect to ϵ .

- all Malliavin derivatives of derivatives with respect to ϵ are Skorohod integrable.

Definition 2.1 A family $(\epsilon \mapsto F_\epsilon) \in C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$, which satisfies additionally that the (Malliavin) covariance matrix $\gamma(F_\epsilon)$ is almost surely invertible for $\epsilon \geq 0$ and at $\epsilon = 0$ (but not necessarily off 0)

$$\frac{1}{\gamma(F_0)} \in \mathcal{D}^\infty = \bigcap_{p \geq 1} \bigcap_{n \geq 0} \mathcal{D}^{p,n},$$

is called a family with regular density.

We shall provide the following characteristic (and useful!) example for families with regular density: given a continuous Gaussian process $(S_t)_{t \geq 0}$ with

$$dS_t = (a(t) - \lambda S_t)dt + \sigma(t)dB_t$$

with continuous (deterministic), square integrable functions $a, b : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$, we define the family $(F_\epsilon)_{\epsilon \geq 0}$ for a fixed number $T > 0$ and show by simple calculations that $(F_\epsilon)_{\epsilon \geq 0} \in C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$,

$$F_\epsilon := z - \frac{\eta^2}{2} \int_0^T (1 + \epsilon S_t^2)^2 dt + \eta \int_0^T (1 + \epsilon S_t^2) dB_t,$$

$$\begin{aligned} D_s F_\epsilon &= \eta(1 + \epsilon S_s^2) - \\ &- 2\epsilon\eta^2 \int_s^T (1 + \epsilon S_t^2) S_t \exp(-\lambda(T-t)) \sigma(t) dt + \\ &+ 2\epsilon\eta \int_s^T S_t \exp(-\lambda(T-t)) \sigma(t) dB_t, \end{aligned}$$

$$D_s F_\epsilon|_{\epsilon=0} = \eta,$$

$$\frac{\partial}{\partial \epsilon} F_\epsilon = -\eta^2 \int_0^T (1 + \epsilon S_t^2) S_t^2 dt + \eta \int_0^T S_t^2 dB_t,$$

$$\gamma(F_\epsilon)|_{\epsilon=0} = \eta^2 T.$$

This example will be applied for the generalized Hobson-Rogers model (GHR).

A more sophisticated example is given by the following structure, which resembles a slightly modified version of the original Hobson-Rogers model (HR):

$$F_\epsilon := z - \frac{1}{2} \int_0^T \sigma(S_t)^2 dt + \int_0^T \sigma(S_t) dB_t,$$

$$dS_t = \left(-\frac{1}{2}\sigma(S_t)^2 - \lambda S_t\right)dt + \sigma(S_t)dB_t$$

with $\sigma(s) = \eta(1 + \epsilon s^2)^{1/2} \exp(-\frac{\epsilon^2 s^2}{M})$ for some large constant M . Hence σ is C^∞ -bounded and bounded and we obtain $(F_\epsilon)_{\epsilon \geq 0} \in C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$. The relevant derivatives at $\epsilon = 0$ read as follows.

$$D_s F_\epsilon|_{\epsilon=0} = \eta,$$

$$\frac{\partial}{\partial \epsilon} F_\epsilon|_{\epsilon=0} = - \int_0^T \frac{\eta^2 S_t^2|_{\epsilon=0}}{2} dt + \int_0^T \frac{\eta S_t^2|_{\epsilon=0}}{2} dB_t,$$

$$\gamma(F_\epsilon)|_{\epsilon=0} = \eta^2 T,$$

where $(S_t)_{t \geq 0}$ at $\epsilon = 0$ is particularly simple, namely a mean-reverting Gaussian process,

$$dS_t = \left(-\frac{1}{2}\eta^2 - \lambda S_t\right)dt + \eta dB_t.$$

Theorem 2.1 Given a family $(F_\epsilon)_{\epsilon \geq 0} \in C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$ with regular density. Then there exist random variables $\pi^n \in \mathcal{D}^\infty$ such that for all $\phi \in C_0^\infty(\mathbb{R})$

$$\frac{\partial^n}{\partial \epsilon^n} E(\phi(F_\epsilon))|_{\epsilon=0} = E(\phi(F_0)\pi^n)$$

holds true for $n \geq 0$.

Definition 2.2 The random variable $\pi^n \in \mathcal{D}^\infty$ is called n th Malliavin weight for differentiation with respect to the parameter ϵ .

Remark 2.1 If π^n is a polynomial of integrated Gaussian polynomials, then the expected value $E(\phi(F_0)\pi^n)$ can be calculated in two steps: first an ordinary Gaussian integral applied to a polynomial on some \mathbb{R}^n , second the integration of this result with respect to Lebesgue measure on $[0, T]^m$. Both procedures are numerically cheap and yield quick and good results even for complicated stochastic differential equations.

The applications which we have in mind are certainly solutions of standard stochastic differential equations of the type

$$dZ_t^{x,\epsilon} = V(\epsilon, t, Z_t^{x,\epsilon})dt + V^1(\epsilon, t, Z_t^{x,\epsilon})dB_t,$$

where the initial value is given by a real vector $x \in \mathbb{R}^N$ and $(B_t)_{t \geq 0}$ denotes a 1-dimensional Brownian motion. If the vector fields V, V^1 are regular enough, for instance real analytic and C^∞ -bounded, then we can take each coordinate of the solution process at a certain time $T > 0$ – viewed as a family of random variables with respect to $\epsilon \geq 0$ – is an element of $C^\infty(\mathbb{R}_{\geq 0}, \mathcal{D}^\infty)$.

We take the above example with $a = \lambda = 0$ and $b = 1$, $S_0 = 0$, and calculate the outcome for the first and second derivative with respect to ϵ .

$$\begin{aligned}
E(\phi(F_\epsilon)) &= E(\phi(z - \frac{\eta^2}{2}T + \eta B_T)) \\
&\quad \frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} E(\phi(F_\epsilon)) \\
&= E(\phi(z - \frac{\eta^2}{2}T + \eta B_T) \delta(\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon \frac{\eta}{\eta^2 T})) \\
&= \frac{1}{\eta T} E(\phi(z - \frac{\eta^2}{2}T + \eta B_T) B_T (-\eta^2 T + \eta \int_0^T B_t^2 dB_t)) + \\
&\quad + \frac{1}{\eta T} E(\phi(z - \frac{\eta^2}{2}T + \eta B_T) \int_0^T (\eta B_s^2 + 2\eta \int_s^T B_t dB_t) ds) \\
&= \frac{1}{T} E(\phi(z - \frac{\eta^2}{2}T + \eta B_T) B_T (-\eta T + \frac{B_T^3}{3} - \int_0^T B_t dt)) + \\
&\quad + \frac{1}{T} E(\phi(z - \frac{\eta^2}{2}T + \eta B_T) (B_T^2 T - \frac{T^2}{2})),
\end{aligned}$$

which has a simple polynomials structure.

For the second derivative we proceed as follows: We observe that two ingredients for Skorohod integral can

be well-calculated, namely

$$\begin{aligned} \frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} \delta \left(\frac{\partial}{\partial \epsilon} F_\epsilon \frac{D_s F_\epsilon}{\gamma(F_\epsilon)} \right) &= \delta \left(\frac{\partial^2}{\partial \epsilon^2} \Big|_{\epsilon=0} F_\epsilon \frac{1}{\eta T} \right) + \\ &+ \delta \left(\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon \frac{D_s \frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon}{\eta^2 T} \right) - \\ &- \delta \left(\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon \frac{\eta}{\eta^4 T^2} \frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} \gamma(F_\epsilon) \right), \end{aligned}$$

and

$$\delta \left(\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon \frac{\eta}{\eta^2 T} \delta \left(\frac{\partial}{\partial \epsilon} \Big|_{\epsilon=0} F_\epsilon \frac{\eta}{\eta^2 T} \right) \right)$$

as above. Again we shall obtain a simple polynomial structure.

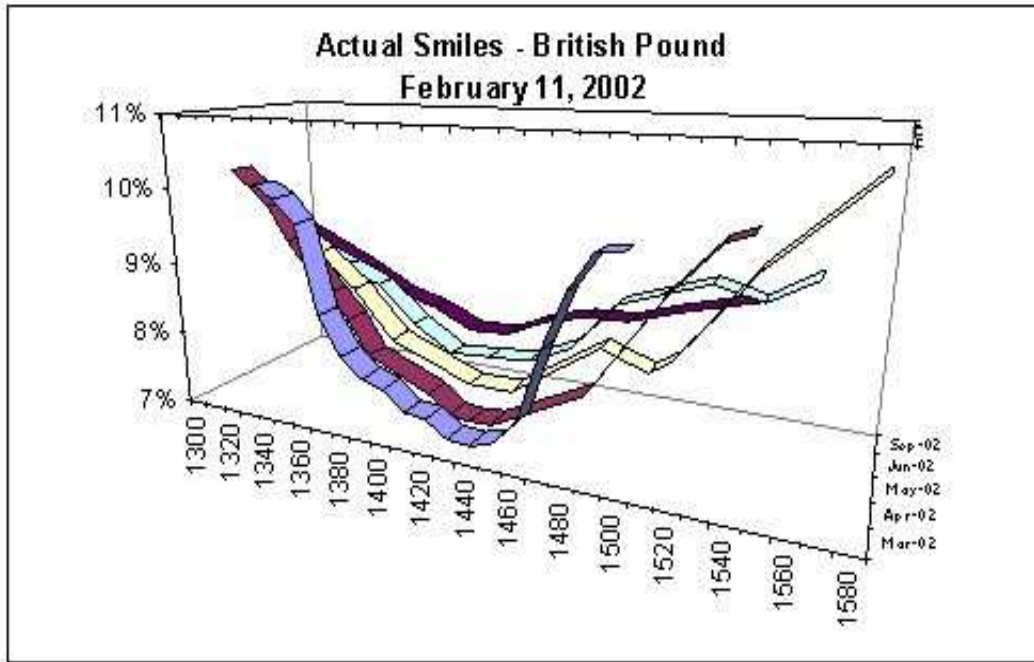


Figure 1: Market Data - Implied Volatilities

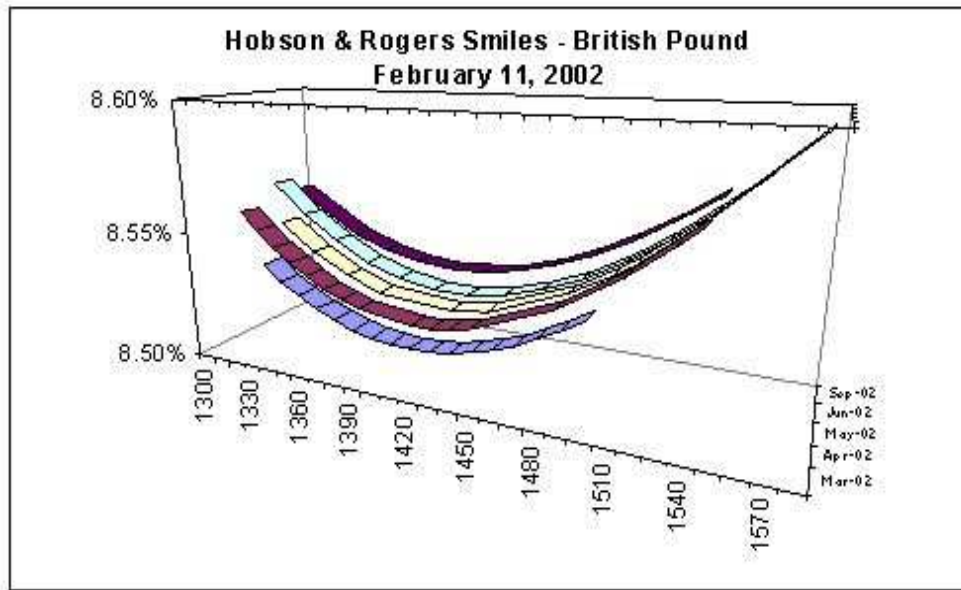


Figure 2: Smiles on microscopic scale

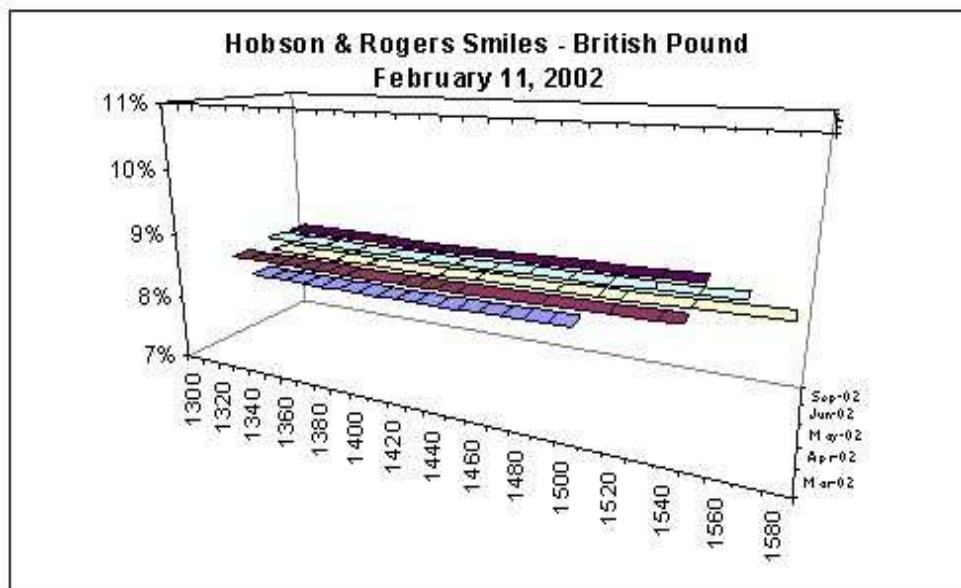


Figure 3: Smiles on appropriate scale

3 GHR-Model

The generalized Hobson-Rogers model reads in the martingale measure as follows.

$$\begin{aligned}dZ_t &= -\frac{1}{2}\sigma_1(S_t)^2 dt + \sigma_1(S_t)d\widetilde{B}_t \\dS_t &= \mu(S_t)dt + \sigma_2(S_t)d\widetilde{B}_t \\Z_0 &= z, S_0 = s\end{aligned}$$

with the following specification,

$$\begin{aligned}\sigma_1(s) &= \eta(1 + \epsilon\beta s^2) \\ \sigma_2(s) &= \chi\eta \\ \mu(s) &= -\frac{\eta^2}{2} - \lambda s\end{aligned}$$

for fixed $\epsilon \geq 0$. In contrast to the HR-model we are additionally given two positive parameters $\chi \geq 1$ and $\beta \in [0, \frac{1}{2}]$ (even though only the product $\epsilon\beta$ enters into the formulas).

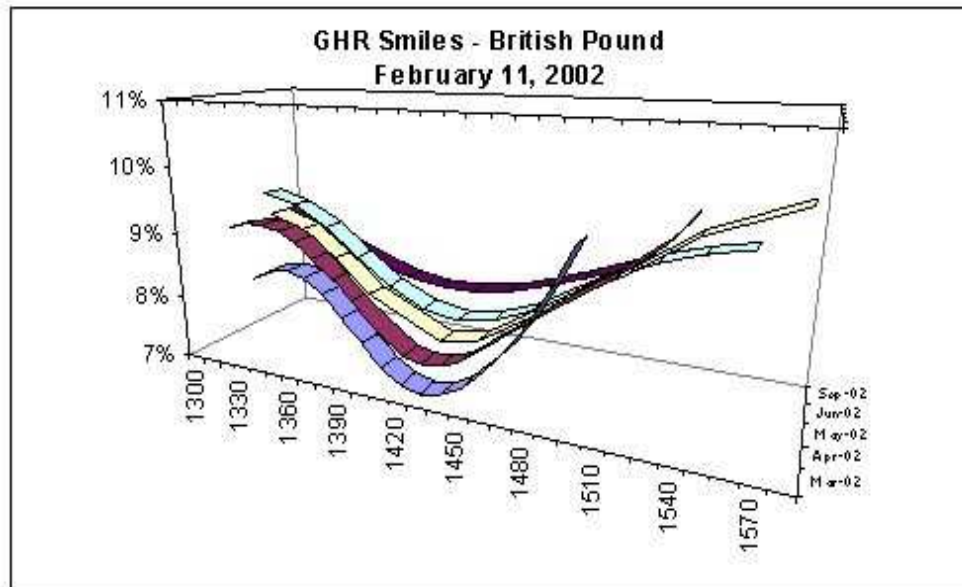


Figure 4: Smiles in GHR-model

With our method we obtain the previous data fit quickly...