

Stopping of Integral Functionals of Diffusions and a "No-Loss" Free Boundary Formulation

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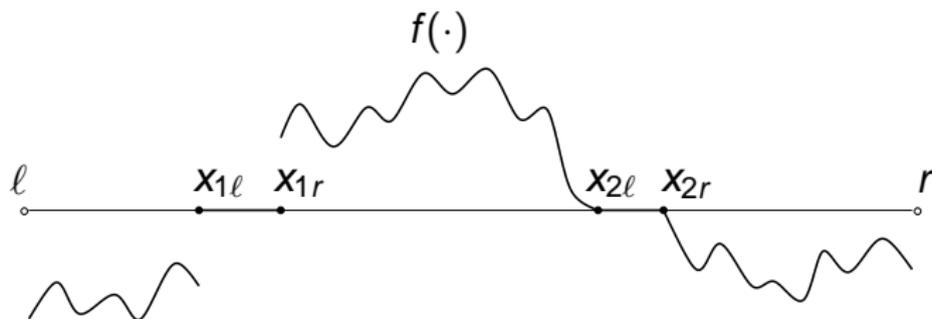
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Formulation of the Problem

$$V^*(x) = \sup_{\tau} \mathbf{E}_x \int_0^{\tau} e^{-\Lambda_u} f(X_u) du \quad (\text{OS})$$

- $dX_t = \mu(X_t) dt + \sigma(X_t) dW_t, \quad \mathbf{P}_x(X_0 = x) = 1$
- $X_t \in \mathbf{J} := (\ell, r)$
- $\Lambda_t = \int_0^t \lambda(X_u) du$
- $\lambda: \mathbf{J} \rightarrow [0, \infty)$

Terminology



In this case we say that f has a two-sided form

Examples:

Graversen, Peskir, and Shiryaev (2000)

Karatzas and Ocone (2002)

Assumptions on μ , σ , f , and λ

Assumptions on μ and σ :

$$\sigma(\mathbf{x}) \neq 0 \quad \forall \mathbf{x} \in \mathcal{J}, \quad \frac{1}{\sigma^2} \in L^1_{loc}(\mathcal{J}), \quad \frac{\mu}{\sigma^2} \in L^1_{loc}(\mathcal{J})$$

Assumptions on f and λ :

$$\frac{f}{\sigma^2}, \frac{\lambda}{\sigma^2} \in L^1_{loc}(\mathcal{J}) \quad (*)$$

Explanation of (*):

(*) $\iff (F_t)$ and (Λ_t) are well defined and finite until ζ

$$F_t = \int_0^t f(X_u) du, \quad \Lambda_t = \int_0^t \lambda(X_u) du$$

ζ is the explosion time of X

Outline

"No-loss" free boundary formulation

Explicit study of a subclass of stopping problems

Notation

For $\alpha, \beta \in \mathbf{J}$, $\alpha < \beta$, we set

$$\tau_{\alpha, \beta} = \inf\{t \geq 0: X_t \leq \alpha \text{ or } X_t \geq \beta\}$$

Standard free boundary

(SFB):

$$\frac{\sigma^2(\mathbf{x})}{2} V''(\mathbf{x}) + \mu(\mathbf{x}) V'(\mathbf{x}) - \lambda(\mathbf{x}) V(\mathbf{x}) = -f(\mathbf{x}),$$
$$\mathbf{x} \in (\alpha, \beta)$$

$$V(\mathbf{x}) = 0, \quad \mathbf{x} \in \mathcal{J} \setminus (\alpha, \beta)$$

$$V'_+(\alpha) = V'_-(\beta) = 0$$

The aim:

If (V, α, β) is a solution, then $V = V^*$ and $\tau_{\alpha, \beta}$ is optimal in (OS)

Modifying free boundary

$$\frac{\sigma^2(\mathbf{x})}{2} V''(\mathbf{x}) + \mu(\mathbf{x}) V'(\mathbf{x}) - \lambda(\mathbf{x}) V(\mathbf{x}) = -f(\mathbf{x})$$

for ν_L -a.a. $\mathbf{x} \in (\alpha, \beta)$

$$V(\mathbf{x}) = 0, \quad \mathbf{x} \in \mathcal{J} \setminus (\alpha, \beta)$$

$$V'_+(\alpha) = V'_-(\beta) = 0$$

The aim:

If (V, α, β) is a solution, then $V = V^*$ and $\tau_{\alpha, \beta}$ is optimal in (OS)

"No-loss" free boundary

V' is absolutely continuous on $[\alpha, \beta]$

$$\frac{\sigma^2(x)}{2} V''(x) + \mu(x) V'(x) - \lambda(x) V(x) = -f(x)$$

for ν_L -a.a. $x \in (\alpha, \beta)$

$$V(x) = 0, \quad x \in J \setminus (\alpha, \beta)$$

$$V'_+(\alpha) = V'_-(\beta) = 0$$

The aim:

If (V, α, β) is a solution, then $V = V^*$ and $\tau_{\alpha, \beta}$ is optimal in (OS)

"No-loss" free boundary

(FB):

V' is absolutely continuous on $[\alpha, \beta]$

$$\frac{\sigma^2(x)}{2} V''(x) + \mu(x) V'(x) - \lambda(x) V(x) = -f(x)$$

for ν_L -a.a. $x \in (\alpha, \beta)$

$$V(x) = 0, \quad x \in J \setminus (\alpha, \beta)$$

$$V'_+(\alpha) = V'_-(\beta) = 0$$

The aim:

If (V, α, β) is a solution, then $V = V^*$ and $\tau_{\alpha, \beta}$ is optimal in (OS)

Main results

Theorem (Verification Theorem)

Suppose f has a two-sided form.

Let (V, α, β) be a solution of (FB). Then

- *it is unique*
- $V^* = V$
- $\tau_{\alpha, \beta}$ *is a unique optimal stopping time in (OS)*

Theorem ((FB) is "no-loss")

If (OS) has an optimal stopping time of the form τ_{α^, β^*} , then (V^*, α^*, β^*) is a solution of (FB)*

Related paper: Lamberton and Zervos (2006)

The assumption that f has a two-sided form is essential for the verification theorem

Example

- f does not have a two-sided form
- (V, α, β) is a solution of (FB)
- $V \neq V^*$
- $\tau_{\alpha, \beta}$ is not optimal in (OS)

The subclass of stopping problems

In the sequel $J = \mathbb{R}, \mu \equiv 0, \lambda \equiv 0$

Characteristic conditions

$$(A_1): h(\infty) > h(-\infty)$$

$$(A_2): \text{If } h(\infty) < h(x_{1\ell}), \text{ then } \int_{a_{h(\infty)}}^{\infty} H(y, h(\infty)) dy < 0$$

$$(A_3): \text{If } h(-\infty) > h(x_{2r}), \text{ then } \int_{-\infty}^{b_{h(-\infty)}} H(y, h(-\infty)) dy > 0$$

Here

$$h(x) := - \int_0^x \frac{2f(y)}{\sigma^2(y)} dy \quad \text{and} \quad H(x, c) := h(x) - c$$

Classification

Case 0: (A_1) – (A_3) hold

Case 1: (A_1) does not hold

Case 2: (A_1) holds and (A_2) does not hold

Case 3: (A_1) holds and (A_3) does not hold

Case 0

- (FB) has a unique solution
- (OS) has a unique optimal stopping time and it is two-sided
- The value function and the optimal stopping time are found explicitly

Case 1

- (FB) has no solution
- (OS) has no optimal stopping time
- The value function is found explicitly
- It can be either finite or identically infinite

Case 2

- (FB) has no solution
- (OS) has a unique optimal stopping time, it is one-sided with the unbounded from below stopping region
- The value function is always finite and is found explicitly, together with the optimal stopping time

Case 3

is symmetric to case 2

Thank you for your attention!

Graversen, S. E., G. Peskir, and A. N. Shiryaev (2000).
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Karatzas, I. and D. Ocone (2002).

A leavable bounded-velocity stochastic control problem.

Stochastic Process. Appl. 99(1), 31–51.

Lamberton, D. and M. Zervos (2006).

On the problem of optimally stopping a one-dimensional Itô diffusion.

Submitted.